

第九届中国LHC物理年会

The 9th China LHC Physics Workshop



Computing vision QC in HGCal production

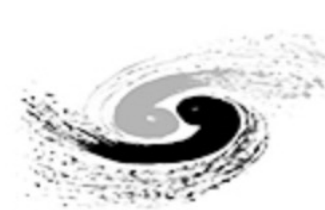
Xuhao Yuan (IHEP)

On behalf of CMS-HGCal IHEP group

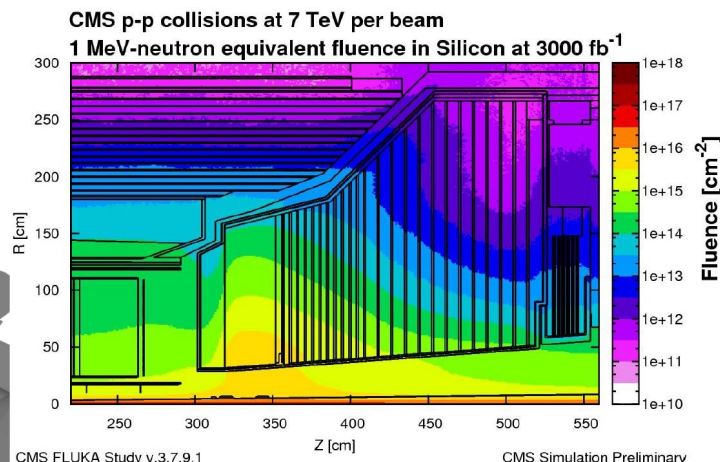
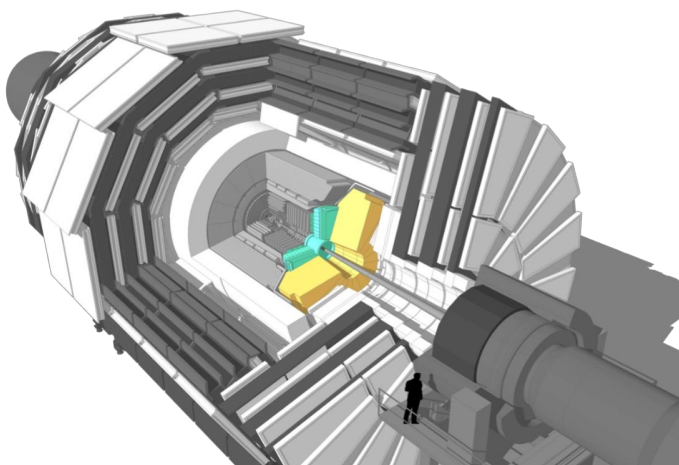
2023-11-17



CMS HGCal project



More details in Feng, Taozhe & Xiao's talks



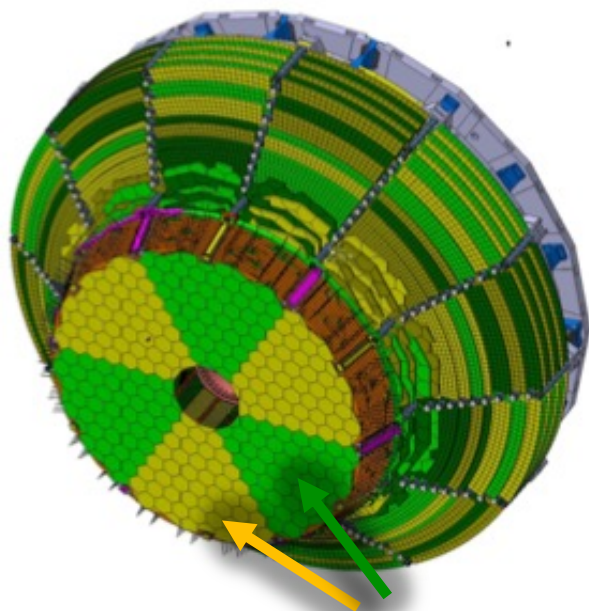
CMS endcap calorimeters: Phase-2 upgrade

- Harsh environment @ HL-LHC:
pile-up ↑, radiation level ↑
- A new endcap calorimeters to be constructed

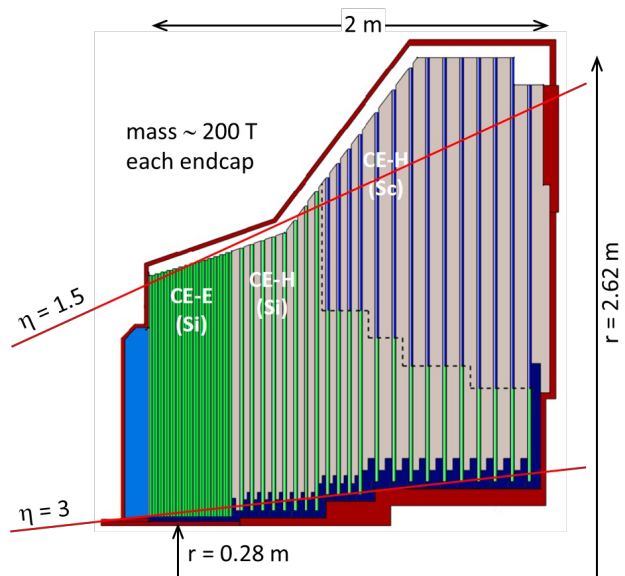
❑ High Granularity Calorimeter: **HGCal**

Key parameters

- Coverage $1.5 < \eta < 3.0$
- Operation @ -30°C
- ~640 m² silicon sensors + ~370 m² scintillator tiles
⇒ 31k Si-modules including spares
- 6.1M silicon channels: 0.5 or 1.1 cm² cell size
+ 240K scintillator-tile-SiPM channels



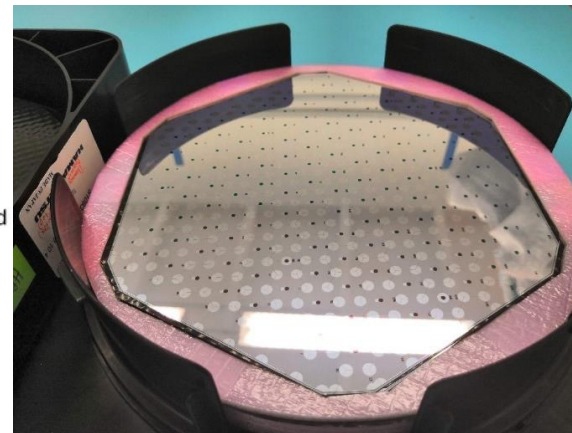
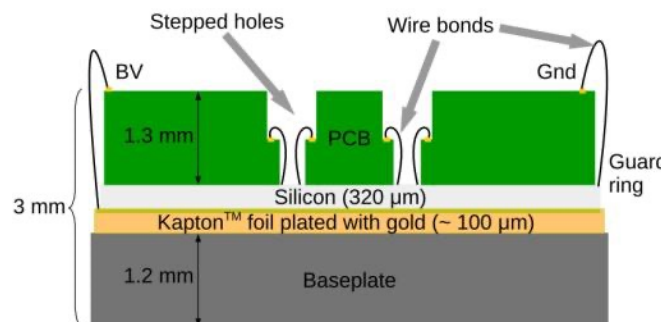
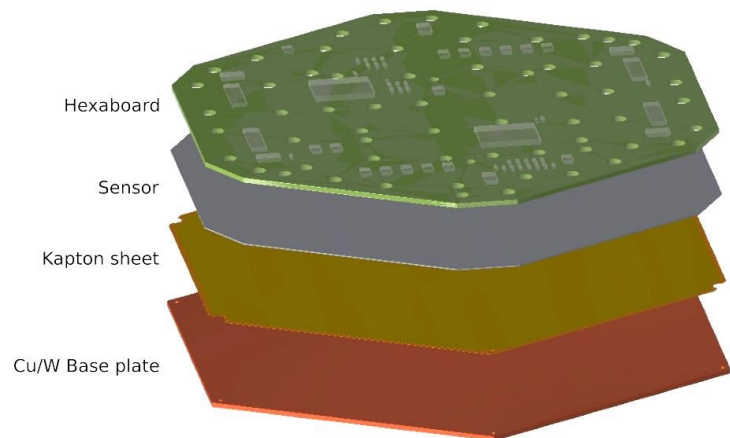
Si-modules



IHEP: focus on silicon modules

- One of Module Assembly Center (MAC), total 6 MACs world wide

Silicon modules



HGCal: ~31K silicon modules

- Module assembly chain established

Vision QC in module assembly

- Sensor: scratches lead to potential damage
- Wire-bonding: multiple wires at the same pad \leftrightarrow cell, single bad wire barely detected by electronic tests
- Encapsulation: glue on wire-bonds for better mechanical stability, QC needed for the glue dispensing





Automatic vision QC on silicon sensor



Visual inspection via microscope

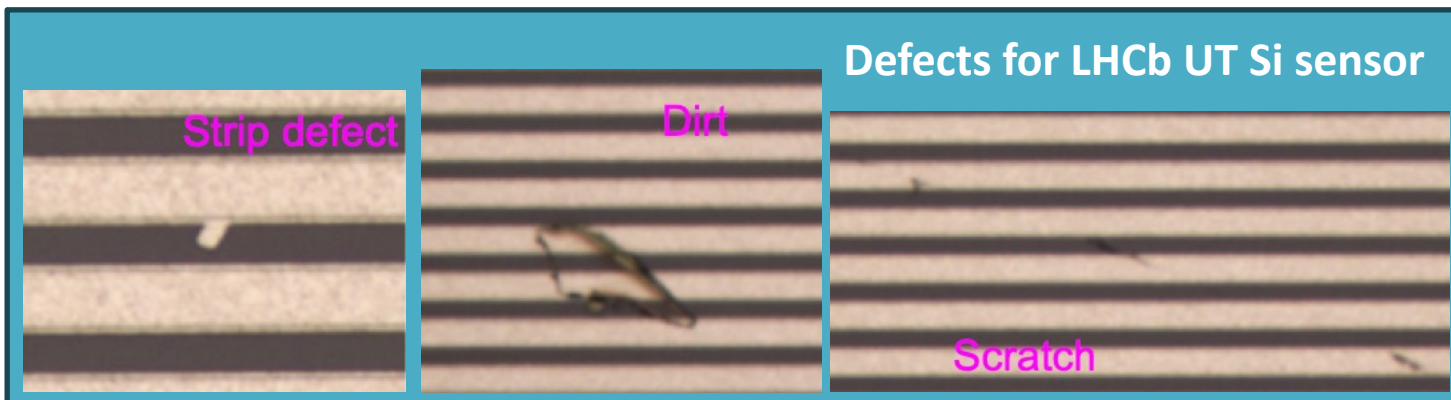
- Traditional manual inspection: huge manpower + low efficiency

An automatic visual inspection method needed

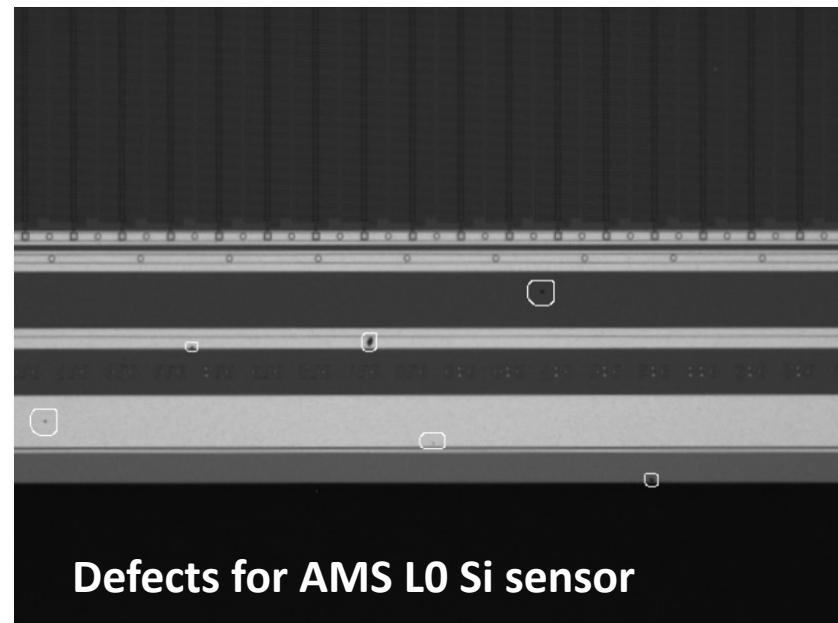
- Firstly developed for LHCb UT silicon strip sensor QC (2016-2018)
- Based on OpenCV package

See the presentation in *Forum on Tracking Detector Mechanics 2019*,
<https://indico.cern.ch/event/775863/contributions/3416994/>

- Updated algorithms for AMS L0 detector. More pixels, more complicated feature, thinner strip line... => but better performance

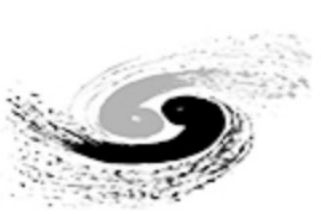


Can we port this method onto HGCal?





Automatic vision QC on HGCal Si sensor



Currently we focus on defects searching on 8" silicon sensor

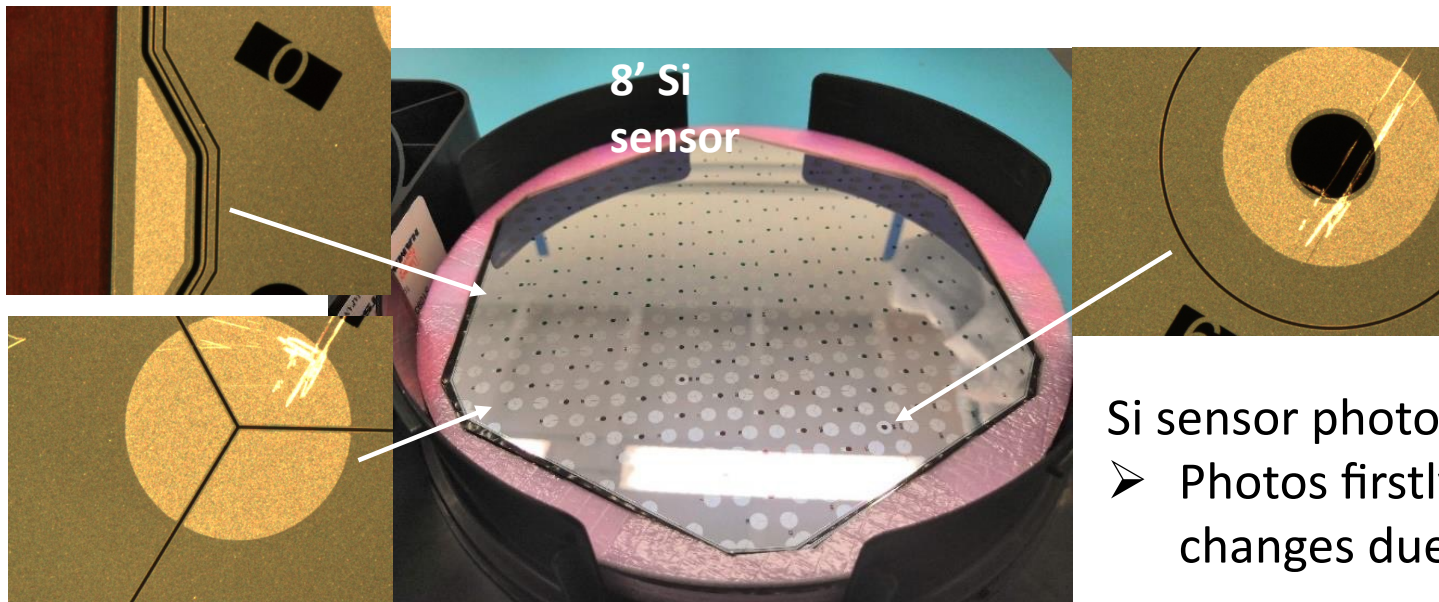
- Vision QC for wire-bonding & encapsulation to be done soon later

OGP ZIP 635 shooting for micro photos

- $O(10^2)$ micro photos in $\sim 0.5h$, only for bonding pad areas



OGP ZIP 635



Si sensor photo features very different along the position

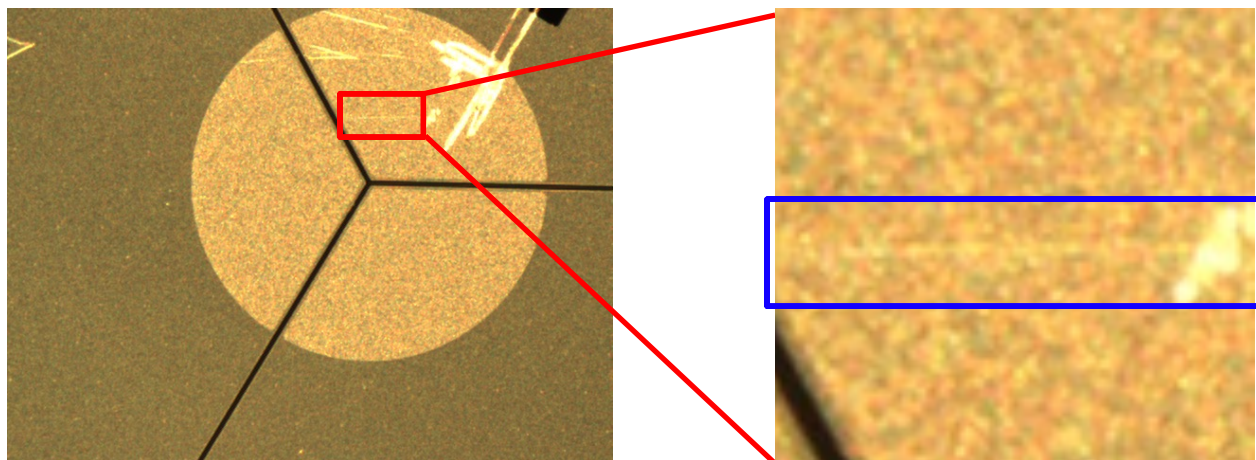
- Photos firstly categorized, processing software with minimal changes due to their features




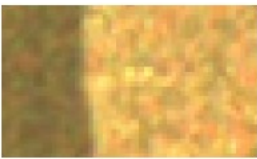


Two-step screening

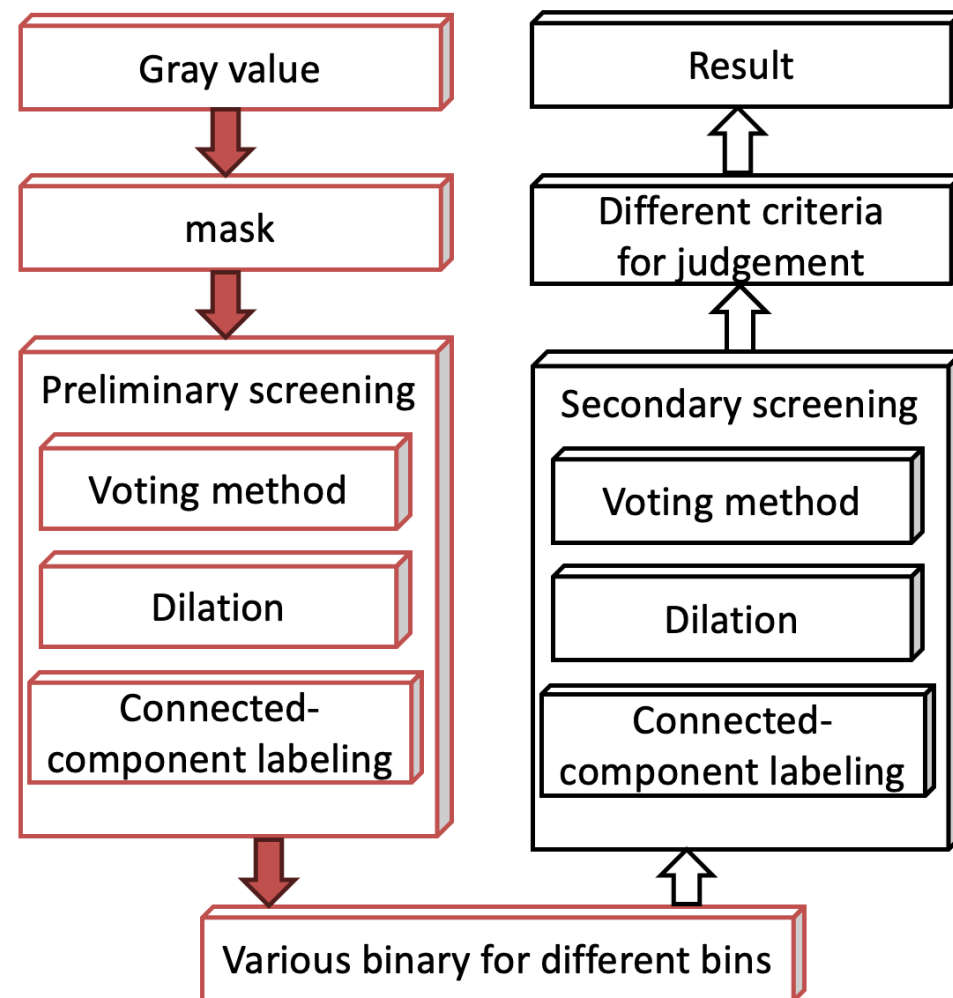


Taking the “Y” shape photo as an example

Challenge from the high-level noise



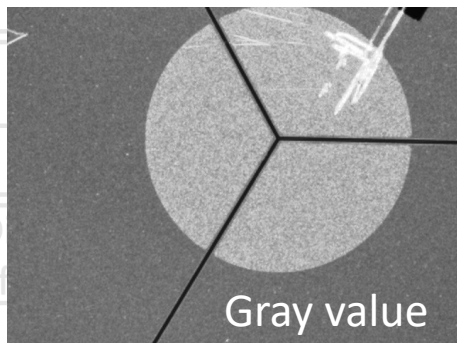
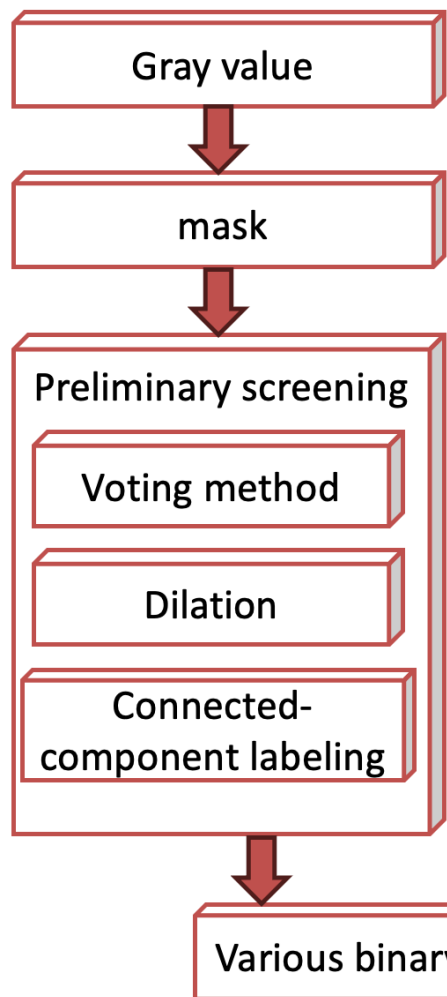
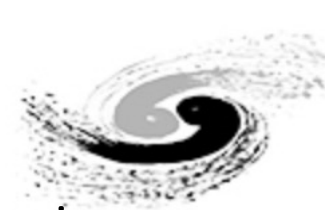
| | color | gray | binary |
|--------------|---|---|--|
| scratches |  |  |  |
| noise points |  |  |  |



Screening performed on photo twice for further noise suppression



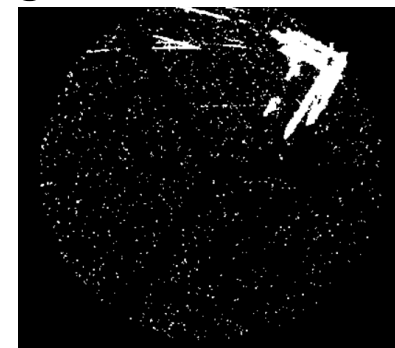
Noise suppression @ 1st screening



Threshold used for inner area



High level noise



If do nothing, light scratches missed



Voting: any pixel with weight less than global average removed

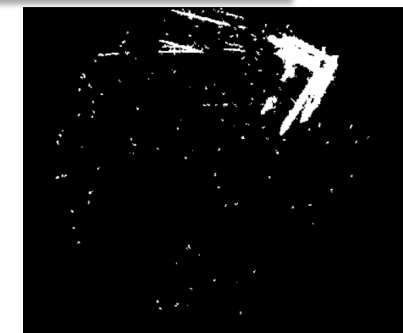
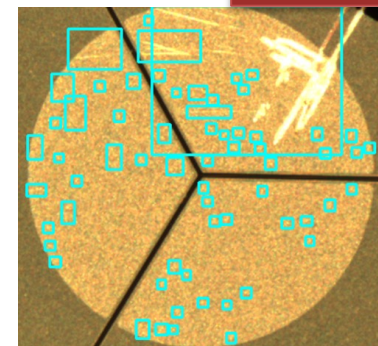
➤ Weight: 1 for white pixel, 0 for black one

Dilation: single pixel expanded into 3x3 pixel

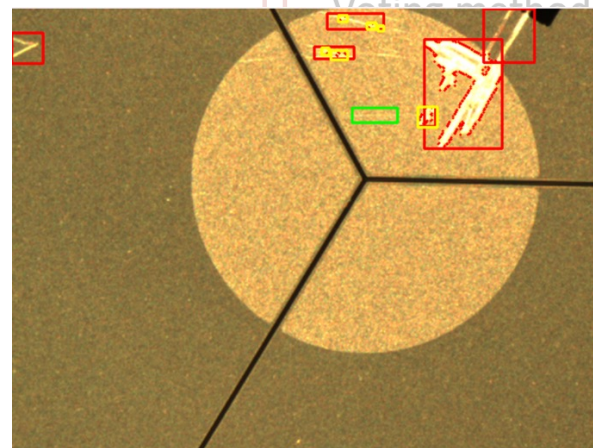
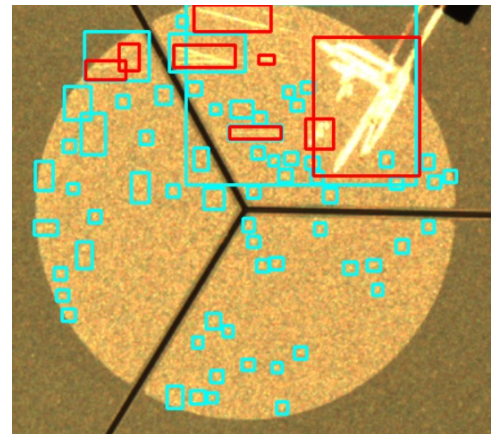
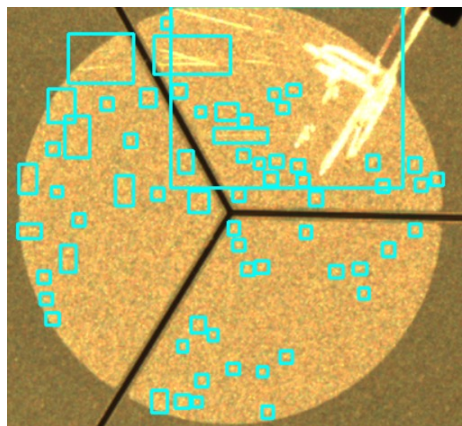
➤ Removed if no connection with others

Noise suppressed

Connected-component labeling and re-do the binary in different boxes



Defects found @ 2nd screening

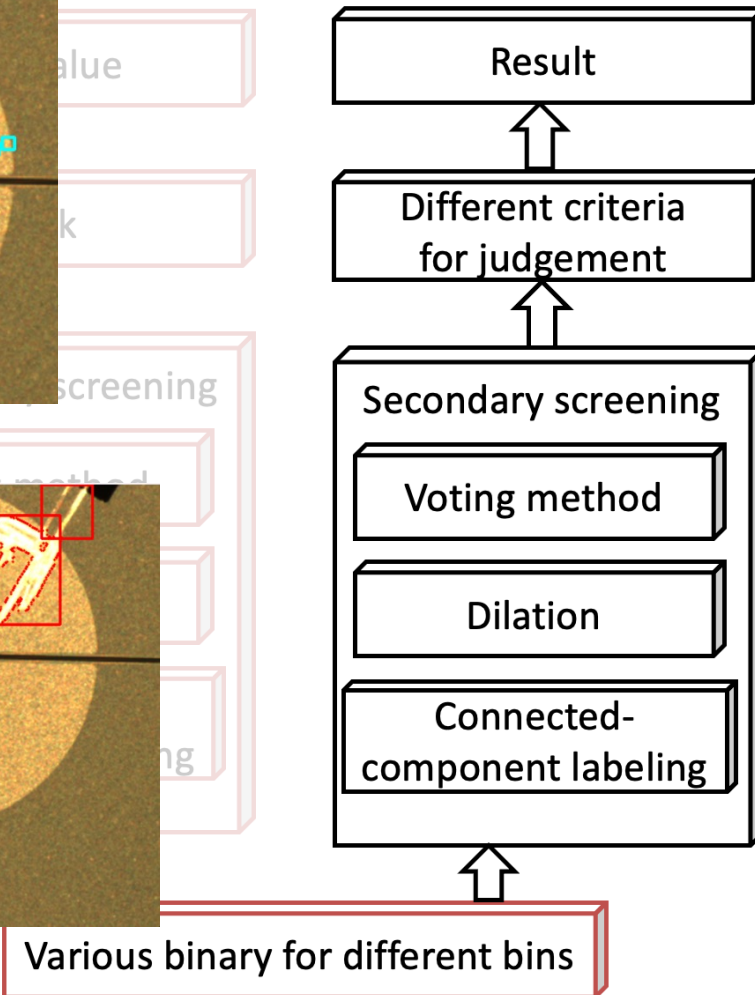


Secondary screening performed in each box

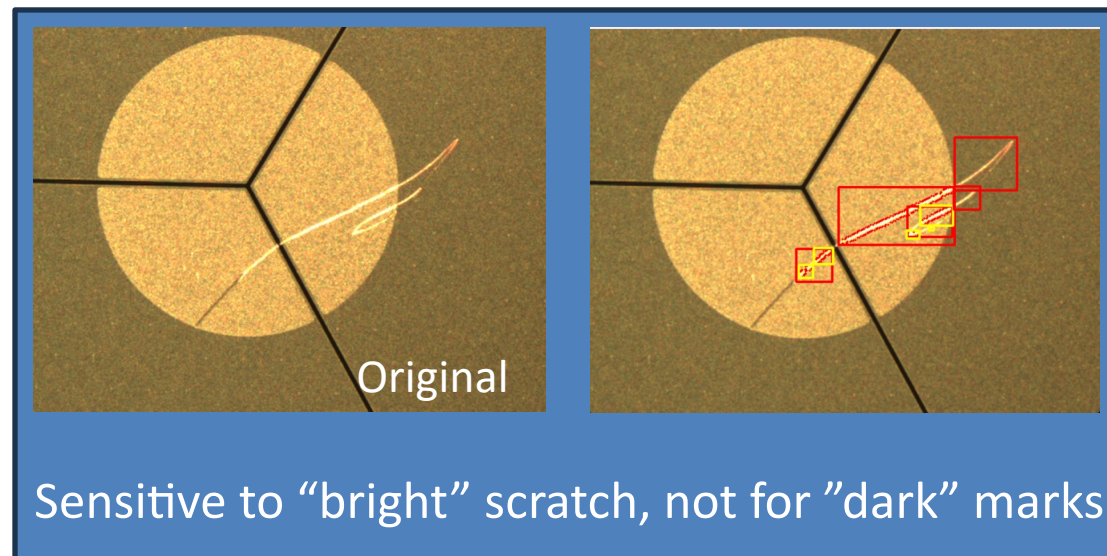
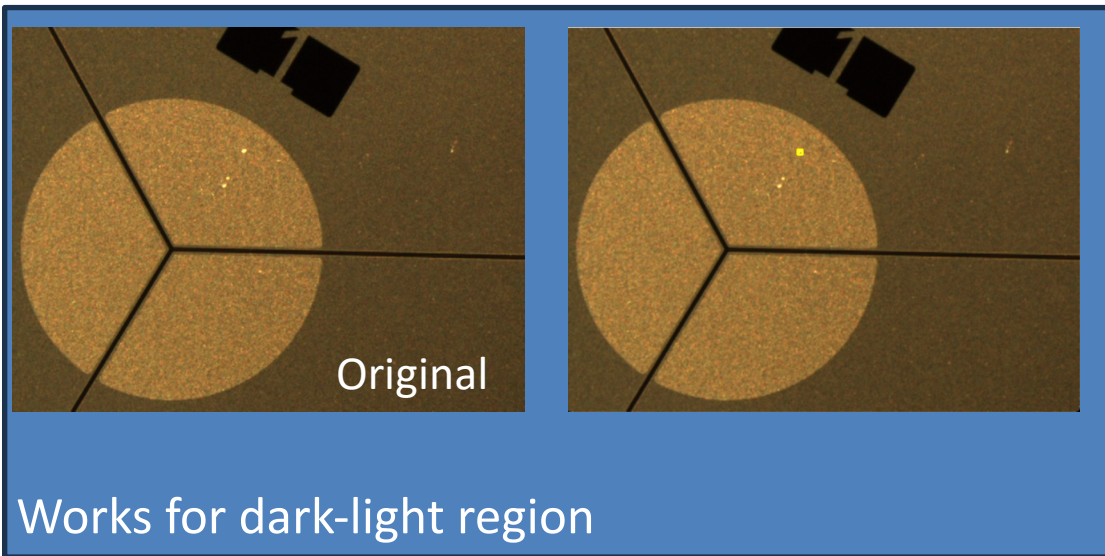
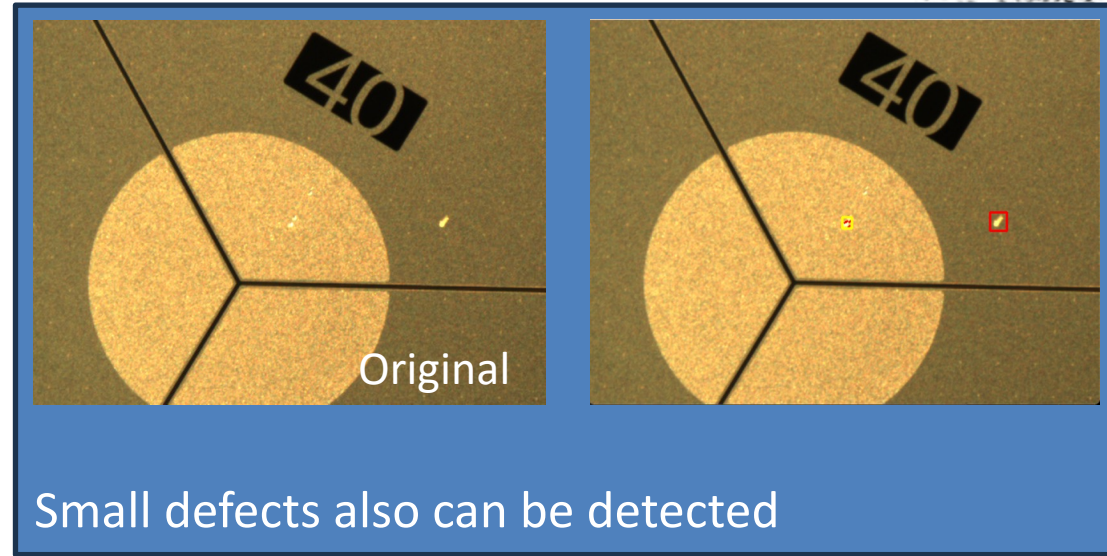
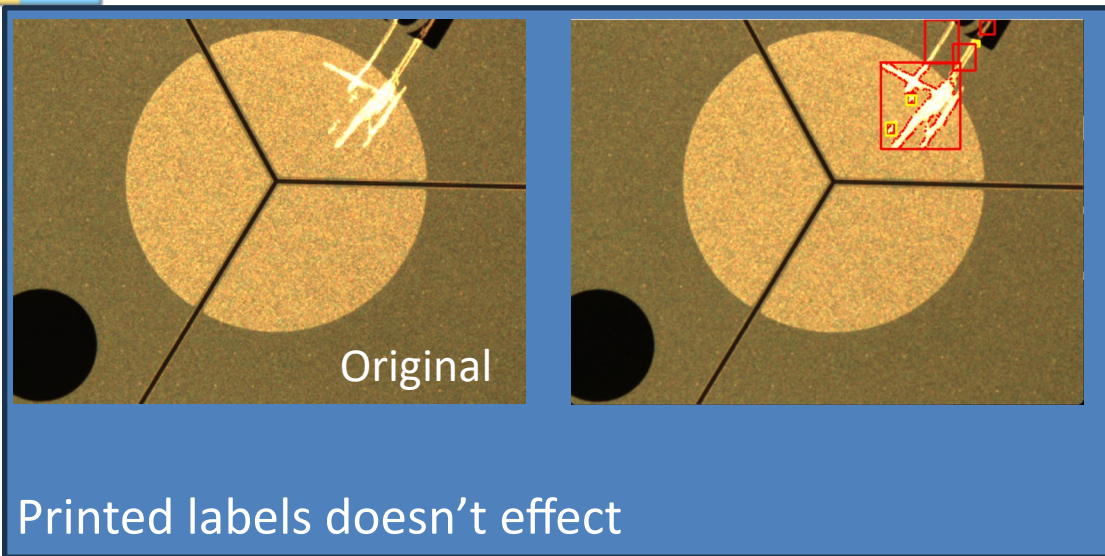
- Further noise suppression and clean feature image obtained

Criteria for defects judgement different

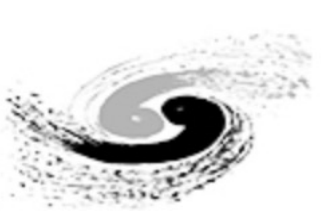
- “Big” component: threshold on area (in red)
- “small” component: “white” ratio in each box
 - Square-like defects: yellow
 - Line-like defects: green



More examples



Summary



Automatic vision inspection for scratches on HGCal silicon sensor developed

- Based on OpenCV and widely used in some other silicon detectors constructions
- Save man power dramatically, with high defects searching efficiency

Done by Shengbo Cao (Shandong Univ.), Changcheng Liu (Jilin Univ.),
Hanbing Liu (Jilin Univ.), Lusen Zhang (Hunan Univ.),

Machine learning method in next step

- Current method still miss some tiny potential scratches \Rightarrow new algorithm may improve
- Final goal: automatic vision check for wire bonding and encapsulation, in which more complicated structure expected



Thank you for your attentions